

ESnet6 High Touch Services

Precision Streaming Network Telemetry

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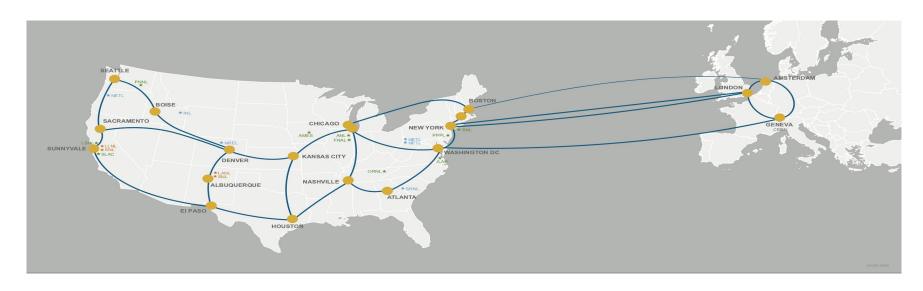
Energy Sciences Network
Lawrence Berkeley National Laboratory

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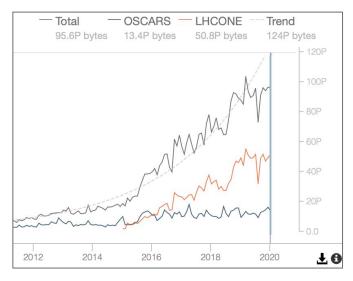
ESnet: DOE's <u>high-performance network</u> (HPN) user facility optimized for enabling big-data science



ESnet provides connectivity to all of the DOE labs, experiment sites, & supercomputers

Increased Need for Programmability

- ESnet's traffic, user-base and the experiments continue to grow in a fast pace
- Computing and data model are also evolving, requiring:
 - fine-grained visibility in real-time
 - application-specific traffic handling
 - programmable, in-network services
- Needs not addressed by existing measurement mechanisms (sampled, aggregated, delayed)
- High Touch Services created to fulfill these needs



Live ESnet usage statistics: my.es.net Total carried: Exabyte/year.

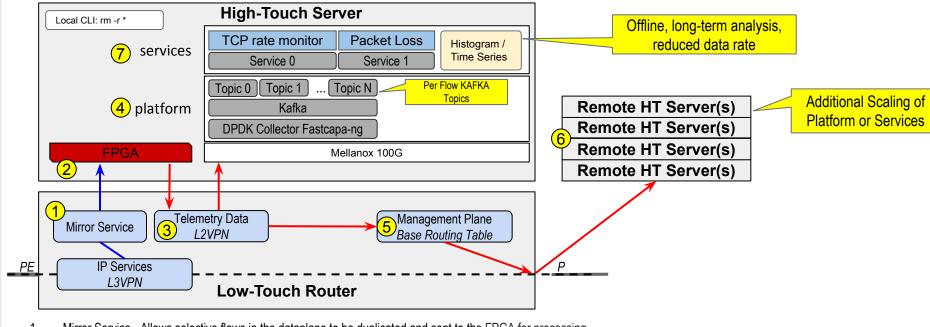


High-Touch Services

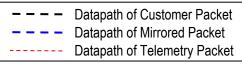
- High-precision, real-time visibility into network traffic
 - Process every packet of interest in real-time
 - Accurate, precision timing (ns precision / accuracy)
 - Software-defined functionality
 - Programmatically deployable and customizable
- In contrast to "low touch" services
 - Fixed function services such as IP packet routing, basic statistics
 - Optimized for speed and low cost, but not flexible
- Technology enablers
 - Software-defined networking
 - Programmable network dataplane hardware with accurate timestamps
 - High-speed packet processing libraries (DPDK, etc.)



ESnet6 High-Touch Architecture Overview



- Mirror Service Allows selective flows in the dataplane to be duplicated and sent to the FPGA for processing.
- 2. Programmable Dataplane (DP) Appends meta-data, timestamps and repackages packet for transmission to Platform code.
- 3. Telemetry Data L2VPN Connect Dataplane and Platform, possibly on different High-Touch Servers.
- Platform Reads telemetry packets from the network and distributes information to High Touch Services.
- Management Plane Base Routing Table Provides connectivity to Remote Servers.
- Remote Server Hosts Platform components or Services (but not a Dataplane). Telemetry data can be directed to Remote Servers.
- Service Reads data from the Platform and performs real-time analysis as well as inserts selected telemetry data into database.





What Programmable "High Touch" Hardware to Use?

- There are a variety of programmable network devices available today. ESnet was looking for the following:
 - 100Gbit/s port speed and roadmap for higher speeds
 - Timing and performance guarantees
 - Easy programming (P4 style)
 - Established vendor with support
- We are currently prototyping using Xilinx FPGAs
 - Alveo U280: 2x100G port, 8GB HBM2 memory
 (3.2 Tbps bandwidth), 32GB DDR4, 1.2M logic cells

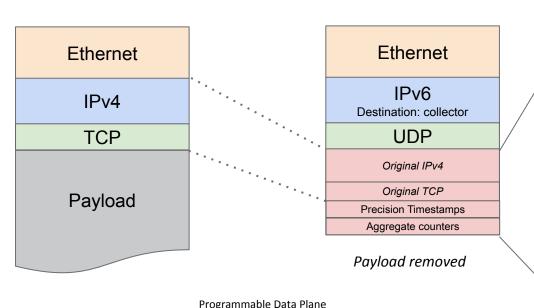




Xilinx U280 FPGA card



Telemetry Producers



Copy of original packet of a TCP flow

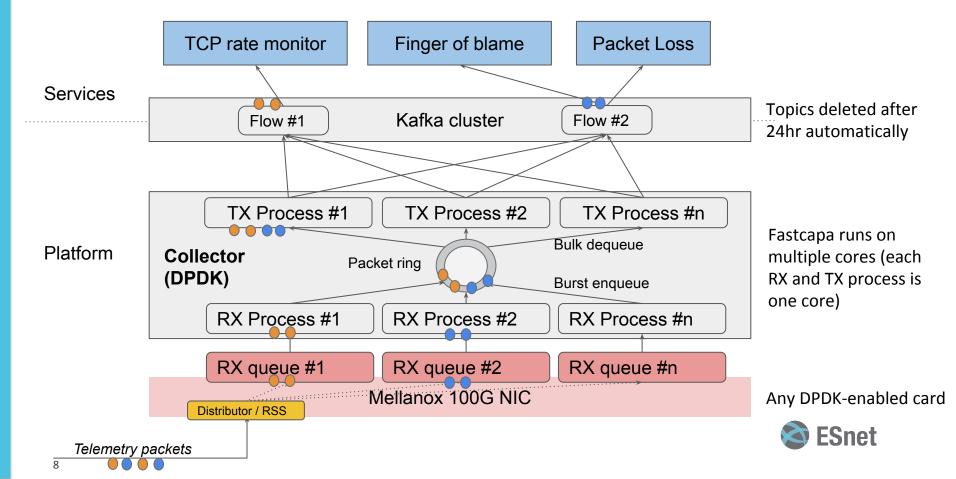
Transforms packets

Packet size	Rate	Telemetry PPS	Telemetry Rate
1500B	10Gb/s	812K	1,079Mb/s
1500B	100Gb/s	8,127K	10,790Mb/s
9000B	10Gb/s	138K	183Mb/s
9000B	100Gb/s	1,383K	1,833Mb/s

High-Touch Telemetry Packet type HighTouchLayer struct { string uint8 VlanId uint16 IngressTimestamp uint64 // IP header of original packet net.IP net.IP // TCP header of original packet TcpSrcPort uint16 TcpDstPort uint16 uint32 TcpSeqNo TcpAckNo uint32 // Aggregate counters FlowPktCount uint64 FlowByteCount uint64 FlowId uint16 Flags uint8

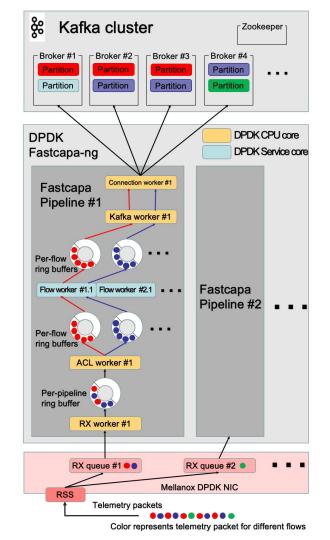
High-Touch Telemetry Record (approximate) ~100 bytes

High Touch Collector Processing



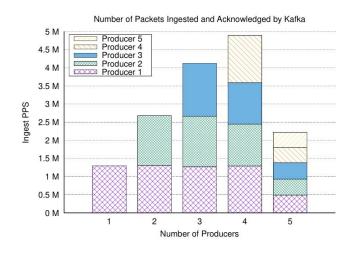
ESnet Fastcapa-ng Internals

- RX queue:
 - NIC dma packets into memory
 - RSS (Receive Side Scaling) applied
- RX worker:
 - pull packet into ring buffers
- ACL worker:
 - classify flows and send them to dedicated rings.
- Flow worker (service cores):
 - process flows using different function: passthrough, sampling, histogram, etc.
 - Flexible N to M mapping of flow to service cores.
- Kafka worker:
 - Combine multiple telemetry packets into large kafka messages.
- Dedicated Kafka connection:
 - maintain TCP connection, message compression task.



Kafka setup and benchmarking

- Docker-compose: bitnami/kafka, JMX
 Exporter, Prometheus, Grafana
- 6 brokers on a single server
- Possible bottlenecks:
 - Librdkafka C client (inside Fastcapa-ng)
 - Docker proxy network
 - CPU Fastcapa and Kafka brokers are on the same host



~5M PPS ingest untuned single server / 6 broker



Use Case #1 TCP Rate and Retransmission Tracking

Motivation:

- Monitoring TCP rate in a per-packet basis
 - Find peaks, abnormal rate in the shortest possible time
- Provide a tool for network operations and engineering
- Finding packet retransmissions as they happen
 - o Is there an issue at ESnet or at the source or destination networks?

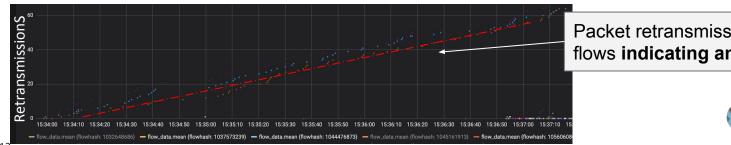


Visualizing Real-Time Telemetry Data

We can plot metrics for every packet in a flow using InfluxDB / Grafana



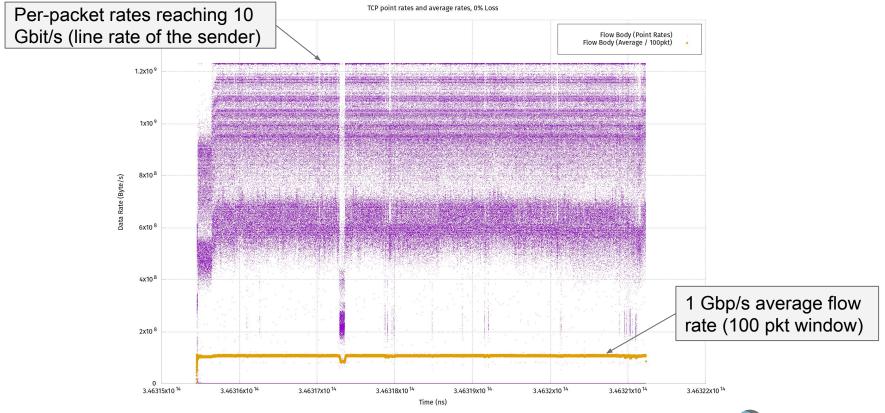
A sample PerfSonar 10Gbit/s test measured by High Touch Rate Monitor



Packet retransmissions for flows indicating an issue



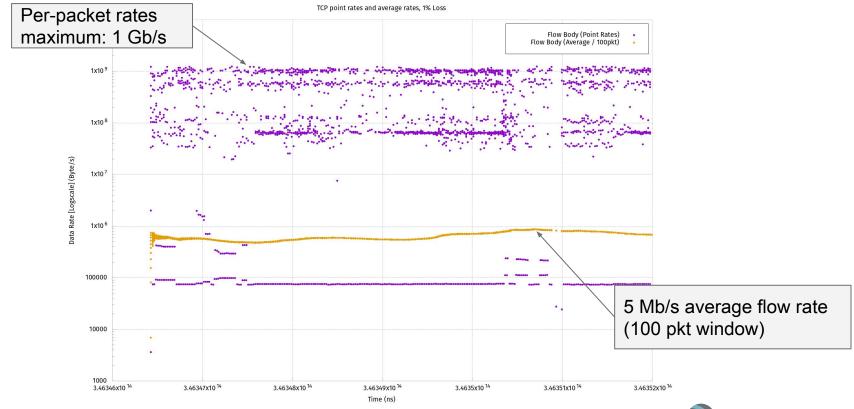
1 Gbps iPerf Flow - 600,000 Packets



Note: Average rate is calculated using a time-weighted average of per-packet rates.



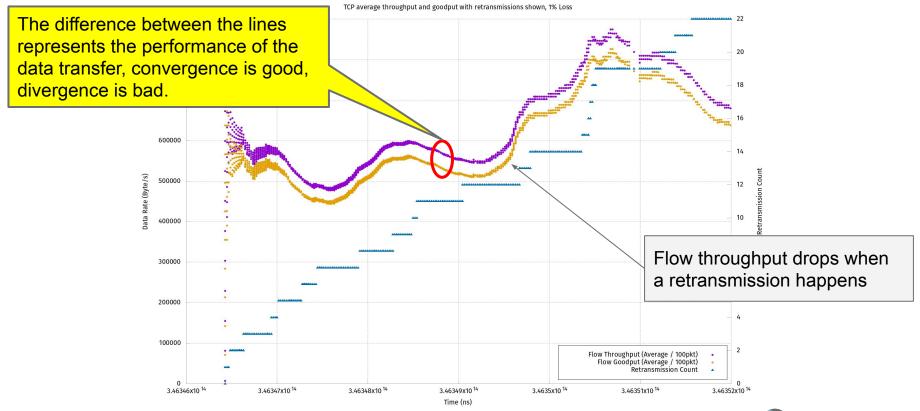
1 Gbps iPerf flow - 1% packet drop



Note: only 23 packets were dropped all together, taking bandwidth down to 5 Mb/s from 1 Gb/s.



1 Gbps iPerf Flow - 1% Packet Drop



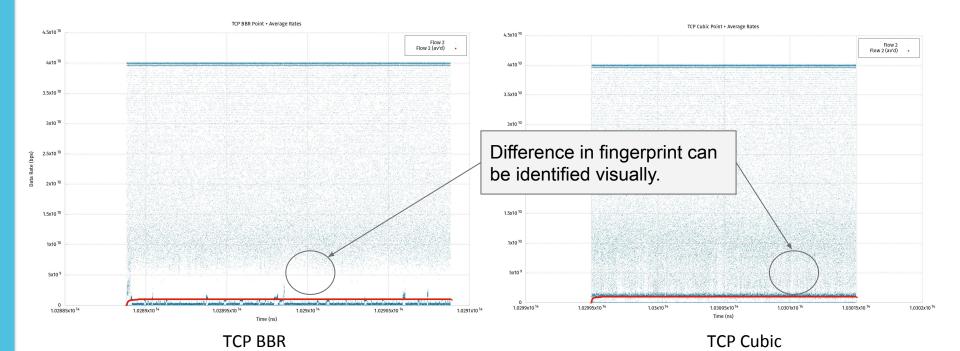


Use Case #2 TCP Congestion Control Identification

- Motivation:
 - Some flows are unable to utilize the available bandwidth
 - TCP flows can take more of their fair-share
- Discovering misconfigured flows (e.g., window parameters, congestion control) will allow us:
 - Tune the configuration of Data Transfer Nodes
 - Notifying our sites automatically (periodic reports) on suboptimal configuration
 - Guide fair usage of the network ("is equal bandwidth share" fair?)



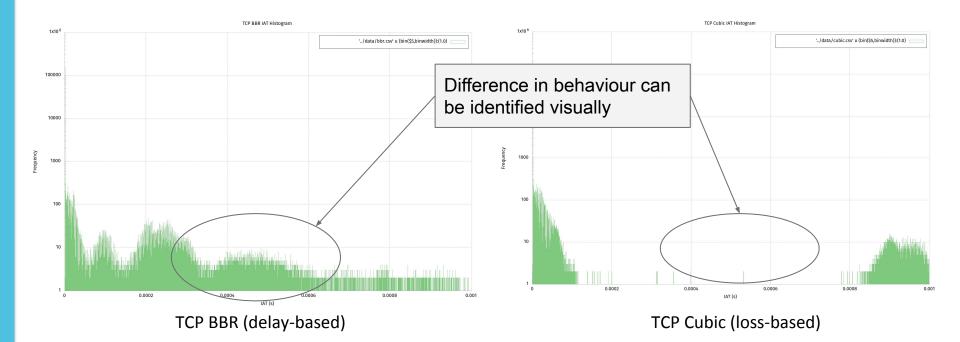
BBR vs Cubic - Point Rates



2 millions of data points shown (around 600.000 points a second generated)



BBR vs Cubic - Inter-Arrival Time Histogram



BBR: inter-packet timing is more widespread than other congestion control algorithms.

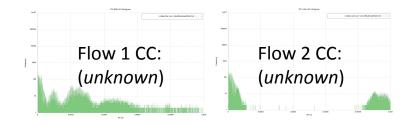


Machine Learning on Aggregated Data

- Aggregated data such as histograms can be used to tell apart congestion control (CC) used by TCP flows
- We are using data plane histograms of inter-arrival times per flow (2000 packets per histogram)
- ML algorithms explored: Convolutional Neural Networks, k-Nearest Neighbors

More details, dataplane architecture, ML code in:

Simpson, Kyle A., Richard Cziva, and Dimitrios P. Pezaros. "Seiðr: Dataplane Assisted Flow Classification Using ML." IEEE GLOBECOM, Taipei, Taiwan (2020).



Input: per-flow histograms of Inter-Arrival Time (IAT)

Machine Learning

(trained with labeled data)

Inference in less than 1 ms in all cases

Flow 1 CC: most likely TCP BBR Flow 2 CC: most likely TCP RENO



High Touch Application Programming

High Touch Applications can be implemented using Kafka
 Streams - an easy way to program real-time applications on stream of data.



• Expressive, highly scalable and fault tolerant API that allows: aggregation, filtering, counting, grouping data...

```
int THRES = 10;
KTable<Windowed<String>, Long> SYNcounts = stream
    .filter((k, telemetry) -> telemetry.isSYN())
    .groupBy((k, telemetry) -> telemetry.getIPDstAddr())
    .windowedBy(TimeWindows.of(Duration.ofSeconds(5)))
    .count(Materialized.with(String(), Long()))
    .filter((key, value) -> value > THRES);
SYNcounts.toStream().to("syn-attacks");
```

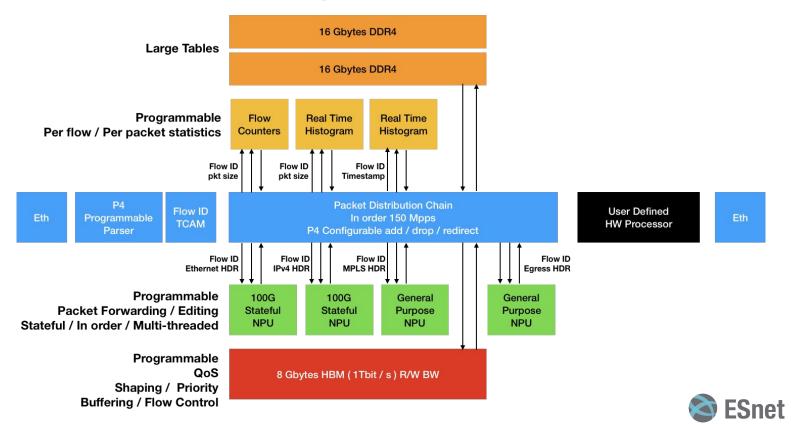
Example: High Touch SYN Flood Detection



High Touch Services **DEMO**



ESnet FPGA Block Diagram - Present and Future



3 models for using FPGAs

Easy

Install a copy of ESnet's telemetry solution. Zero FPGA development. Customize Splunk / Kentik / Grafana / ELK etc..



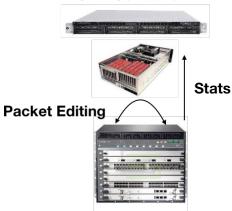




Intermediate

Program the embedded NPUs. Zero FPGA development. FPGA bit file provided. But packet editing is programmable like an SDN switch.

SDN Controller



Advanced

Re-configure the FPGA using P4 and Verilog. User defined hardware.

Custom drivers and applications

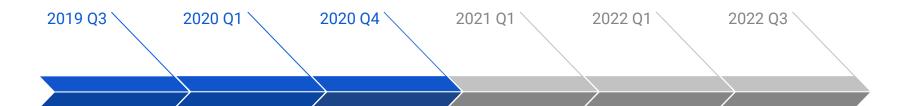


Arbitrary L2-L7 Stateful Ideas





High Touch Services Timeline



Service Design

Technical service design, experimentation with dataplanes and collector software.

Design Validation

Evaluation of the collector software, dataplanes, scoping and prototyping.

Design Refinement

Making the service more robust, implementing a variety of High Touch services, while enhancing scalability, fault tolerance, security, orchestration.

Pre-Pilot

Deploying pilot service, inspecting traffic on selected links (low-traffic customer, high-traffic customer, Splunk integration).

Pre-Deployment

Finalizing a
complete solution:
edge hosts,
programmable
hardware, services
and their
orchestration.

Deployment

Deploying High Touch services.



Questions...



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